



# Graphs: Refresher

CS 4104: Data and Algorithm Analysis

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# Table of contents

1. Motivation

2. Definition

3. Traversal

Breadth-First Search (BFS)

Depth-First Search (DFS)

4. Implementation

5. Conclusion

# Motivation

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- Model pairwise relationships (edges) between objects (nodes).
- Useful in a large number of applications:



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  - Software Systems

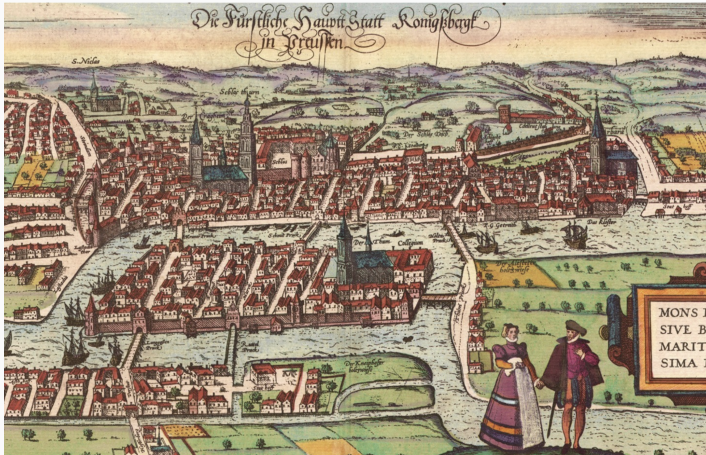
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- Model pairwise relationships (edges) between objects (nodes).
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  - Computer networks
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  - Software Systems
  - Job scheduling

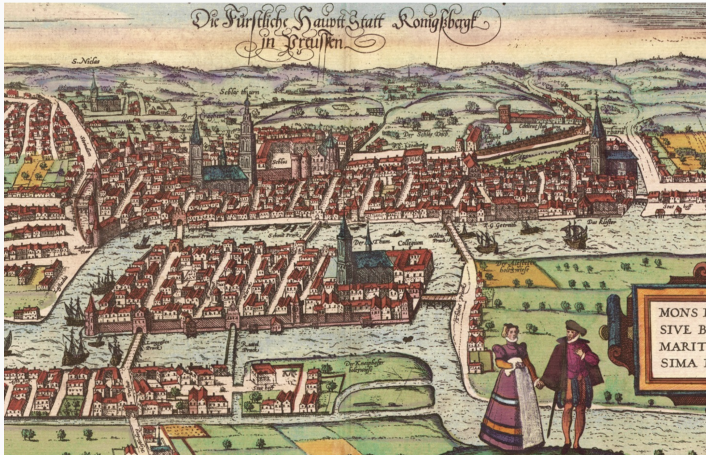
# Why Graphs

- Model pairwise relationships (edges) between objects (nodes).
- Useful in a large number of applications:
  - Computer networks
  - The World Wide Web
  - Social Networks
  - Software Systems
  - Job scheduling
  - Word Morphology, and more
- In CS, we use graph data structure when we want to model non linear data structures

# Euler's Problem



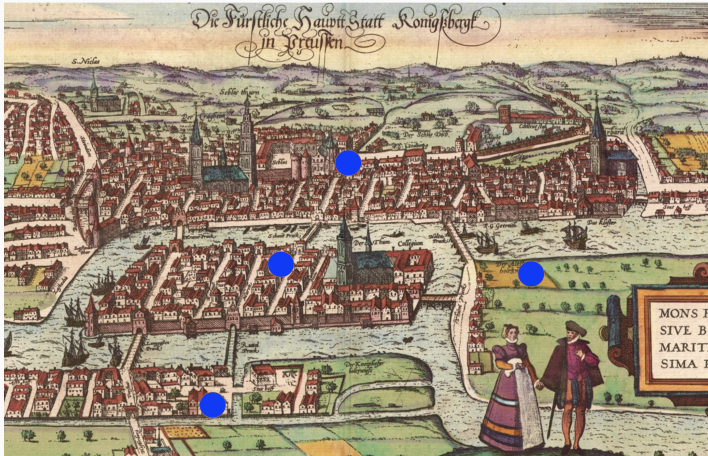
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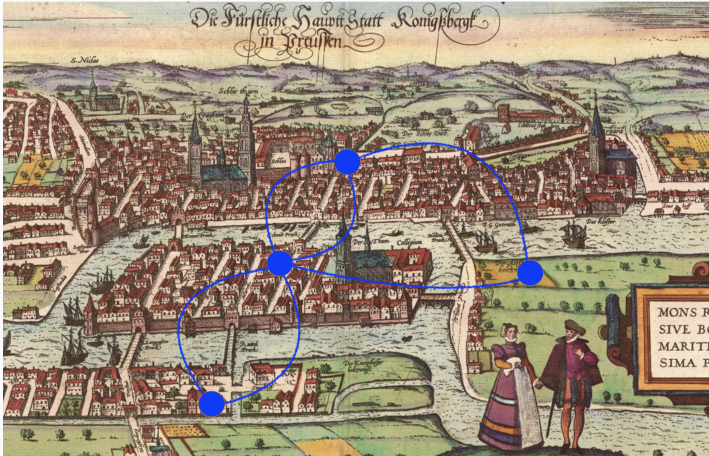
- Devise a walk through the city that crosses each of the bridges exactly once.



# Euler's Problem



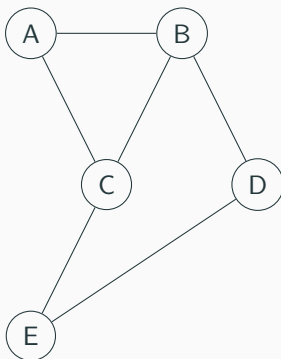
# Euler's Problem



# Definition

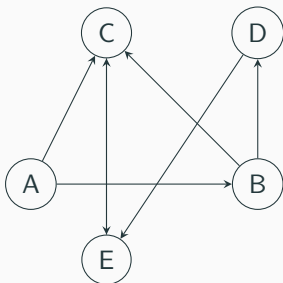
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## Definition: Undirected Graph



- **Undirected graph**  $G = (V, E)$ : set  $V$  of nodes and set  $E$  of edges, where  $E \subset V \times V$
- Elements of  $E$  are **unordered** pairs.
- Edge  $(u, v)$  is incident on  $u, v$ ;  $u$  and  $v$  are neighbours of each other.
- Exactly one edge between any pair of nodes.
- $G$  contains no self loops, i.e., no edges of the form  $(u, u)$ .

## Definition: Directed Graph



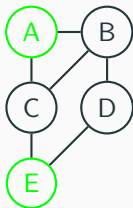
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- Elements of  $E$  are **ordered** pairs.
- Edge  $(u, v)$ :  $u$  is the tail of the edge  $e$ ,  $v$  is its head;  $e$  is directed from  $u$  to  $v$ .
- A pair of nodes may be connected by two directed edges:  $(u, v)$  and  $(v, u)$ .
- $G$  contains no self loops, i.e., no edges of the form  $(u, u)$ .

## Definition: Paths

- A  $v_1 - v_k$  path in an undirected graph  $G = (V, E)$  is a sequence  $P$  of nodes  $v_1, v_2, \dots, v_{k-1}, v_k \in V$  such that every consecutive pair of nodes  $v_i, v_{i+1}$ ,  $1 \leq i < k$  is connected by an edge in  $E$ .

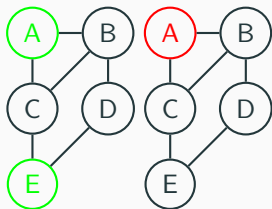
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- A path is simple if all its nodes are distinct.



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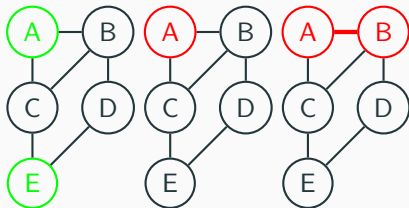
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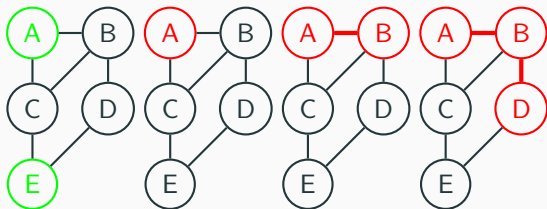
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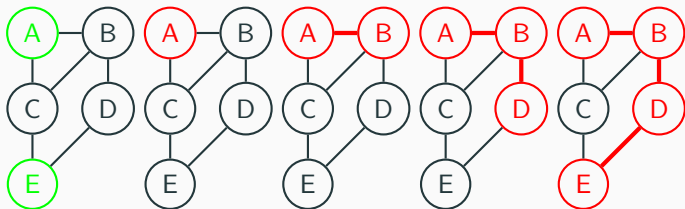
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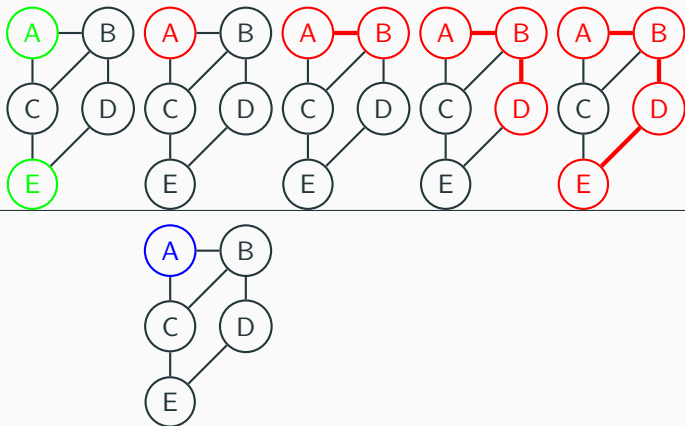
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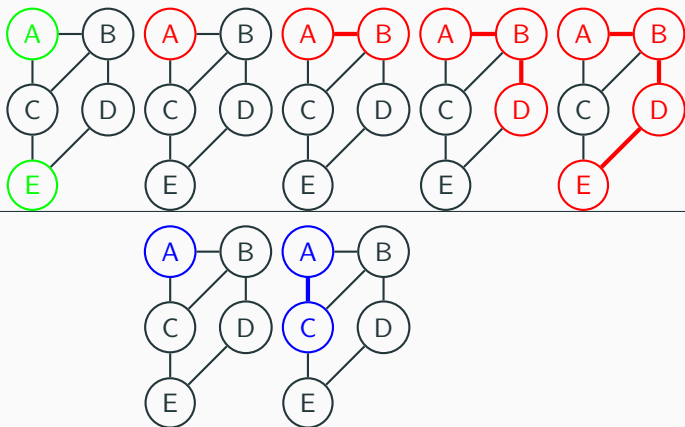
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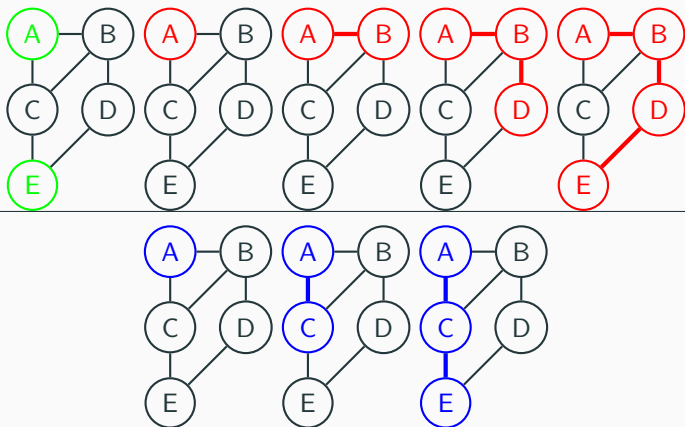
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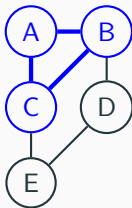


## Definition: Paths

- A cycle is a path where  $k > 2$ , the first  $k - 1$  nodes are distinct, and  $v_1 = v_k$ .

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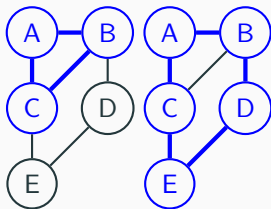
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## Definition: Paths

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## Definition: Connectivity

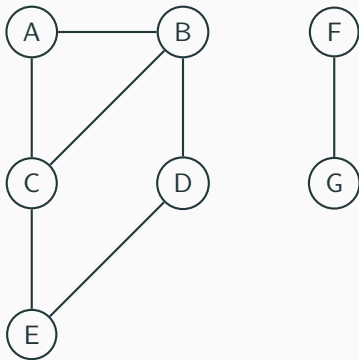
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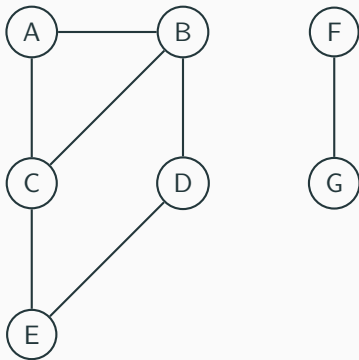
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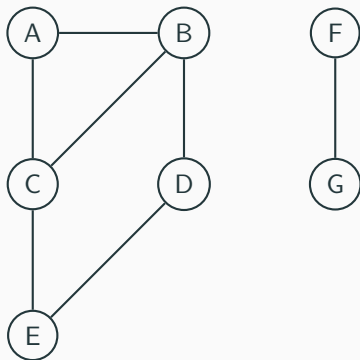
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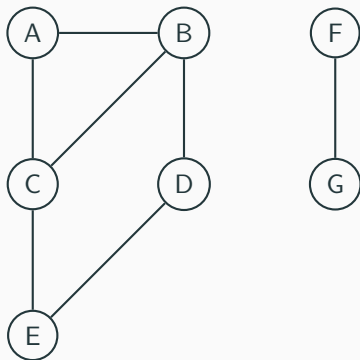


- Similar definitions carry over to directed graphs as well.

## Example: Connectivity

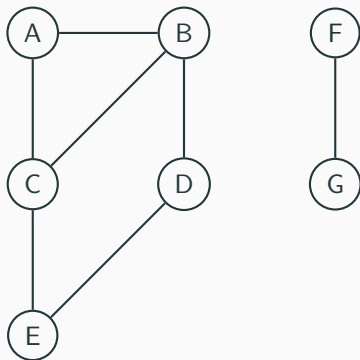


## Example: Connectivity



- Questions

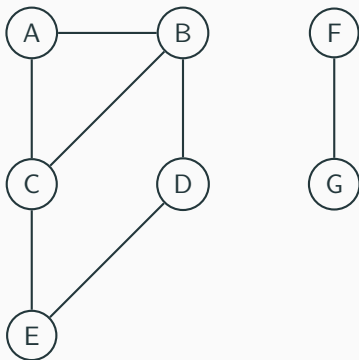
## Example: Connectivity



- Questions
  - Is there a path between F and C:

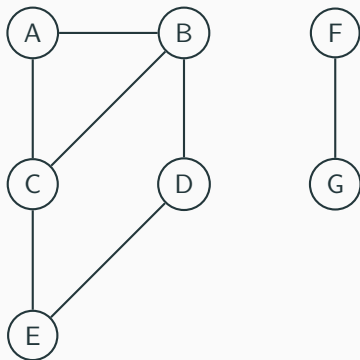


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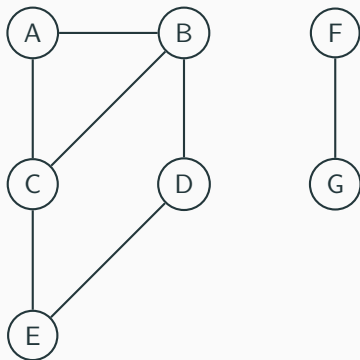
- Questions
  - Is there a path between F and C: **No**

## Example: Connectivity



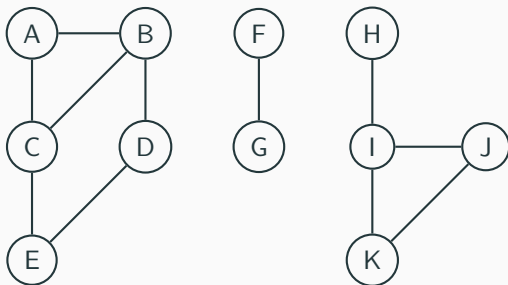
- Questions
  - Is there a path between F and C: **No**
  - What's the distance between D and A :

## Example: Connectivity



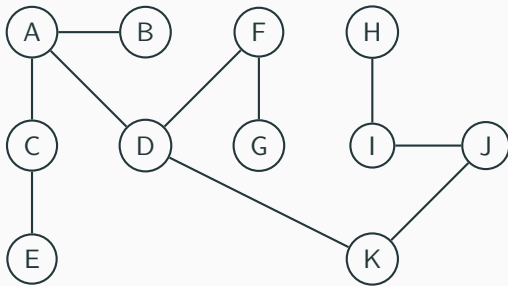
- Questions
  - Is there a path between F and C: **No**
  - What's the distance between D and A : **2**

## Example: Connectivity



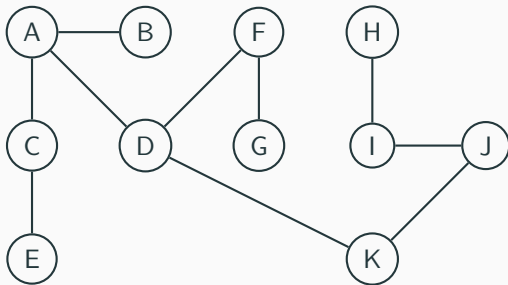
- The **connected component of the graph** containing E is the set of all nodes  $u$  such that there is a path between E and  $u$  in the graph.
- Algorithm for the S-T Connectivity problem: compute the connected component of  $G$  that contains  $S$  and check if  $T$  is in that component.

## Definition: Tree



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- A connected graph  $G$  is said to be a **Tree** if there are no cycles in the graph
- If two of the following are true the third is true.
  - $G$  is a Tree
  - $G$  is connected
  - $G$  does not have a cycle

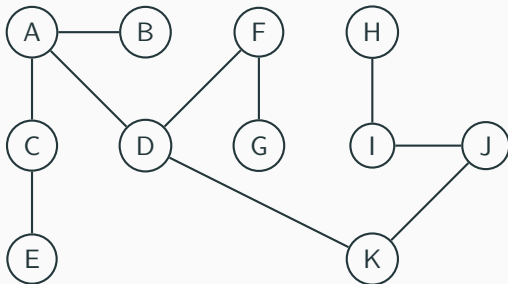
# Traversal

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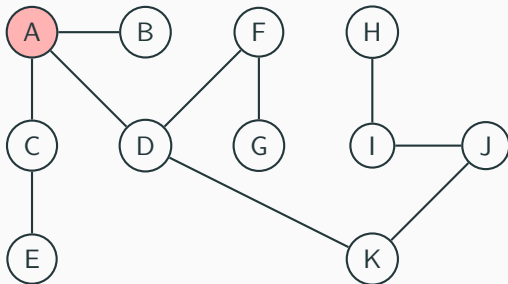
- Breadth-First Search (BFS) is an algorithm for traversing or searching tree or graph data structures.
- It starts at the root (or an arbitrary node in the case of a graph) and explores all neighbors at the present depth prior to moving on to nodes at the next depth level.
- BFS uses a queue to keep track of the next node to explore, ensuring all nodes at the current depth are visited before moving deeper.
- BFS is useful for:
  - Finding the shortest path in unweighted graphs.
  - Finding all nodes within one connected component.



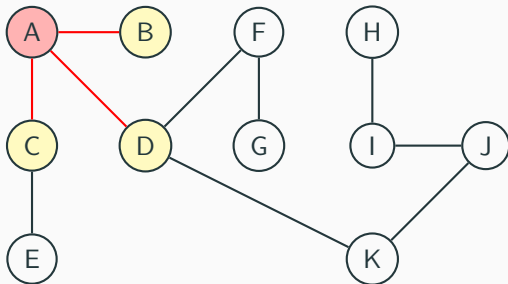
## BFS: Example



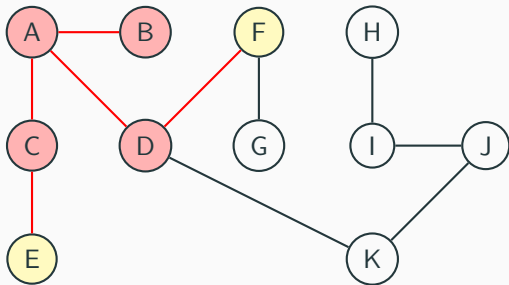
## BFS: Example (Step 1)



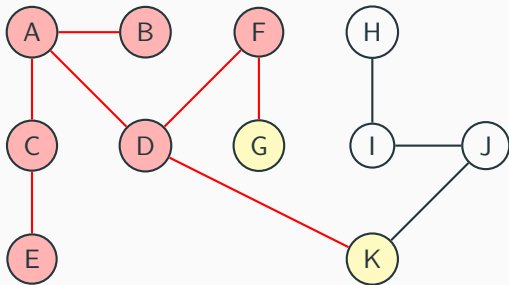
## BFS: Example (Step 2)



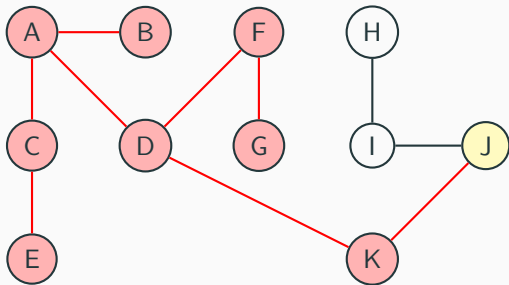
## BFS: Example (Step 3)



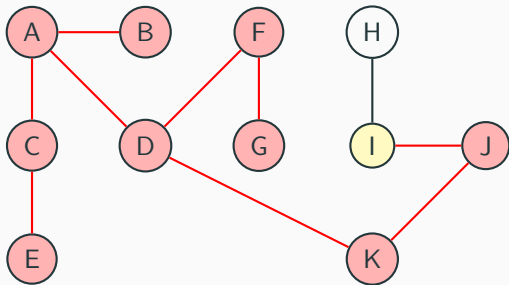
## BFS: Example (Step 4)



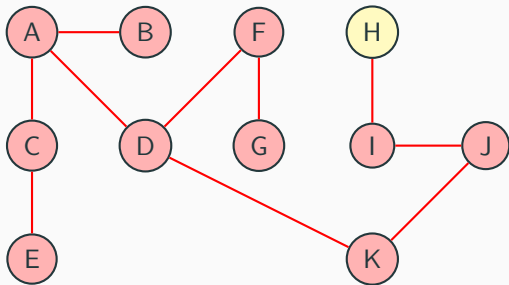
## BFS: Example (Step 5)



## BFS: Example (Step 6)

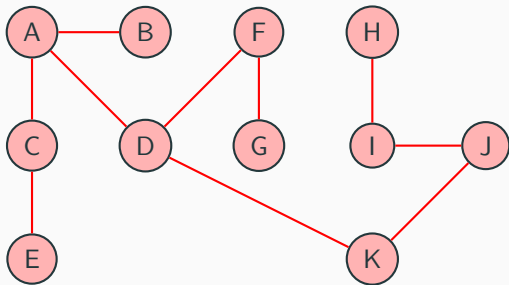


## BFS: Example (Step 7)





## BFS: Example (Step 8)



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**Algorithm 1** Breadth-First Search (BFS)

---

```
1: Input: Graph  $G = (V, E)$ , starting node  $s$ 
2: Output: Set of visited nodes
3:
4: function BFS( $G, s$ ):
5:   let  $Q$  be a queue
6:   initialize  $Q$  with  $s$ 
7:   mark  $s$  as visited
8:   while  $Q$  is not empty do
9:      $v \leftarrow$  dequeue  $Q$ 
10:    for each neighbor  $w$  of  $v$  do
11:      if  $w$  is not visited then
12:        mark  $w$  as visited
13:        enqueue  $w$  into  $Q$ 
14:      end if
15:    end for
16:  end while
```

- **Time Complexity:**  $O(V + E)$ 
  - Each vertex is enqueued and dequeued at most once.
  - Each edge is considered once when exploring the vertex at one end of the edge.
  - Therefore, the total work done is proportional to the sum of the number of vertices and edges.
- **Space Complexity:**  $O(V)$ 
  - We need to store the visited status of each vertex, which requires  $O(V)$  space.
  - The queue can grow to at most  $O(V)$  size if all vertices are at the same level.

- **Shortest path in unweighted graphs:**
  - BFS finds the shortest path (minimum number of edges) from the source node to all other nodes.
  - Useful in scenarios like finding the shortest route in a road network where all roads have the same length.
- **Finding connected components in a graph:**
  - BFS can be used to explore all nodes in a connected component starting from any node in the component.
  - Helps in identifying and counting isolated subgraphs within a larger graph.
- **Level-order traversal of a tree:**
  - In trees, BFS is used for level-order traversal, visiting nodes level by level.
  - Commonly used in scenarios like breadth-first search in AI and game development.

- **Web crawling:**

- BFS is used to crawl web pages starting from a given URL and exploring all reachable pages within a certain depth.
- Ensures that all pages at the current depth are visited before moving to deeper levels.

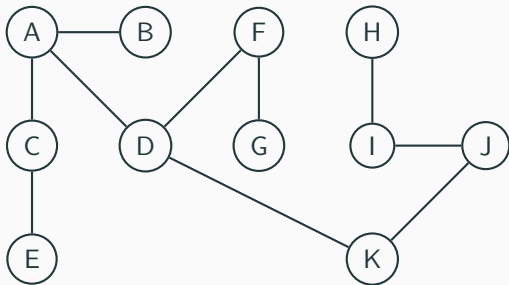
- **Social network analysis:**

- BFS can help in exploring social networks to find shortest connections between individuals.
- Useful for analyzing degrees of separation and influence spread in networks like Facebook or LinkedIn.

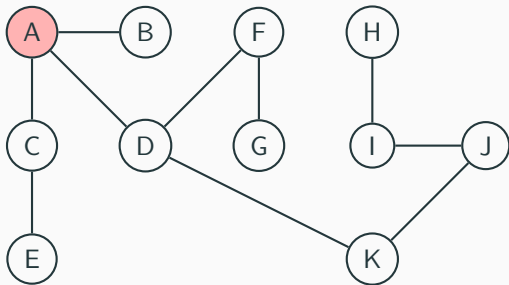
# DFS: Intuition

- Depth-First Search (DFS) is an algorithm for traversing or searching tree or graph data structures.
- It starts at the root (or an arbitrary node in the case of a graph) and explores as far as possible along each branch before backtracking.
- DFS uses a stack (or recursion) to keep track of the path being explored.
- DFS is useful for:
  - Pathfinding in mazes.
  - Topological sorting.
  - Detecting cycles in graphs.

## DFS: Example

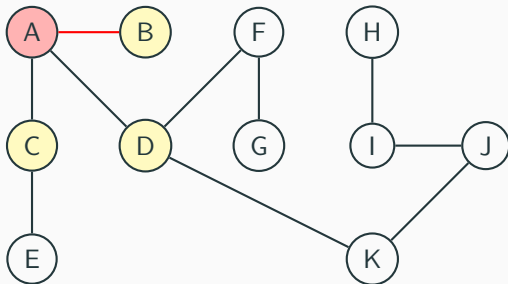


## DFS: Example (Step 1)

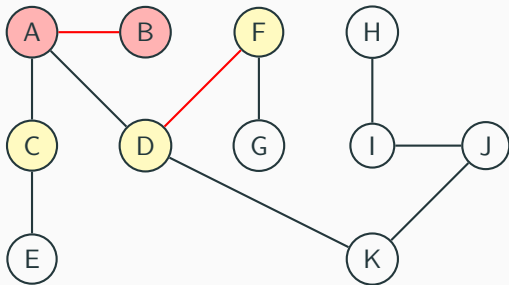




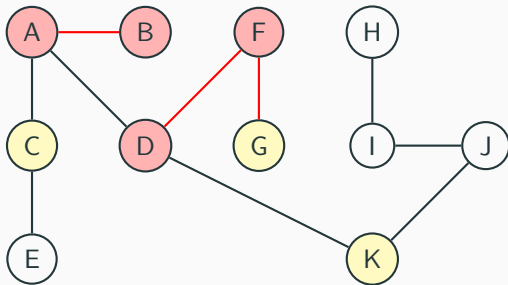
## DFS: Example (Step 2)



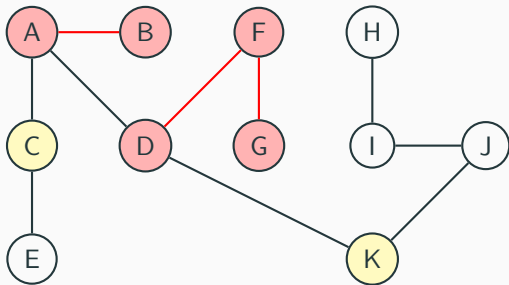
## DFS: Example (Step 3)



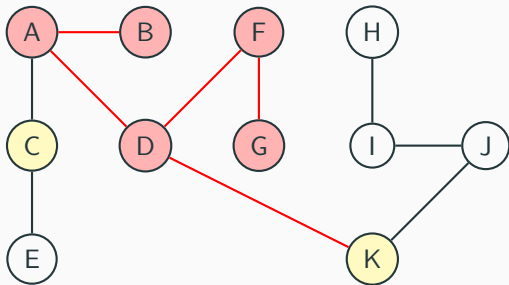
## DFS: Example (Step 4)



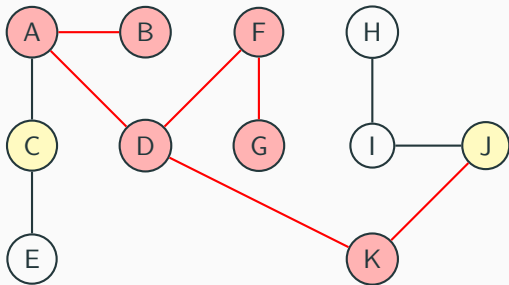
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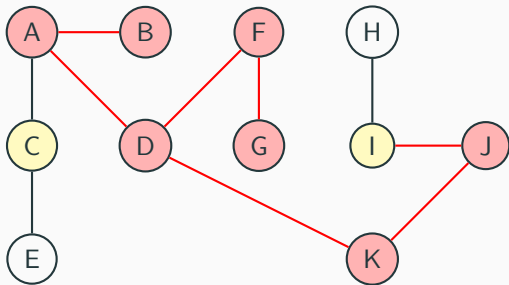
## DFS: Example (Step 6)



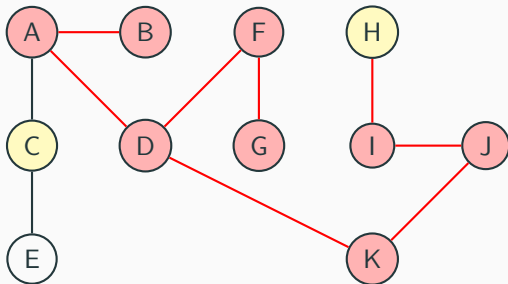
## DFS: Example (Step 7)



## DFS: Example (Step 8)

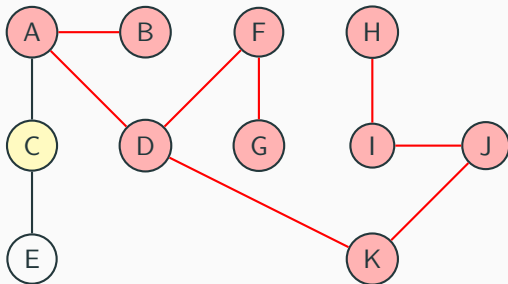


## DFS: Example (Step 9)

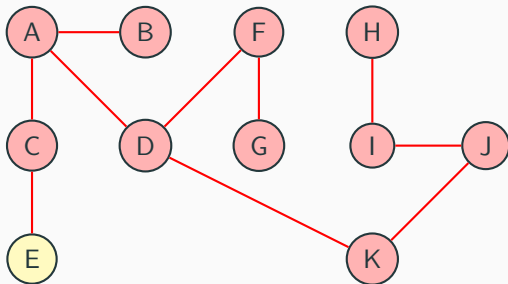




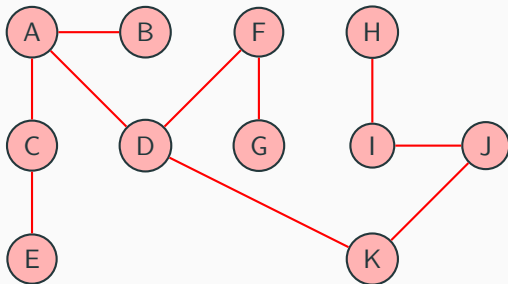
## DFS: Example (Step 10)



## DFS: Example (Step 11)



## DFS: Example (Step 12)



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**Algorithm 2** Depth-First Search (DFS)

---

```
1: Input: Graph  $G = (V, E)$ , starting node  $s$ 
2: Output: Set of visited nodes
3:
4: function DFS( $G, s$ ):
5:   initialize an empty stack  $S$ 
6:   push  $s$  onto  $S$ 
7:   mark  $s$  as visited
8:   while  $S$  is not empty do
9:      $v \leftarrow$  pop  $S$ 
10:    for each neighbor  $w$  of  $v$  do
11:      if  $w$  is not visited then
12:        mark  $w$  as visited
13:        push  $w$  onto  $S$ 
14:      end if
15:    end for
16:  end while
```

- **Time Complexity:**  $O(V + E)$ 
  - Each vertex is pushed and popped from the stack at most once.
  - Each edge is explored once when visiting the vertex at one end of the edge.
  - Therefore, the total work done is proportional to the sum of the number of vertices and edges.
- **Space Complexity:**  $O(V)$ 
  - We need to store the visited status of each vertex, which requires  $O(V)$  space.
  - The stack can grow to at most  $O(V)$  size in the worst case (when the graph is a single path).

- **Pathfinding in mazes:**

- DFS is useful for exploring all possible paths in a maze or labyrinth.
- It helps in finding a path from the start to the end by exploring deeper into the maze.

- **Topological sorting:**

- DFS is used in topological sorting of directed acyclic graphs (DAGs).
- It helps in ordering tasks or vertices such that for every directed edge  $uv$ , vertex  $u$  comes before  $v$ .

- **Detecting cycles in graphs:**

- DFS can detect cycles in both directed and undirected graphs.
- By keeping track of visited nodes and the recursion stack, DFS identifies back edges that form cycles.

- **Finding connected components:**
  - DFS is used to find all vertices in a connected component of an undirected graph.
  - Helps in identifying and counting isolated subgraphs within a larger graph.
- **Solving puzzles with only one solution:**
  - Puzzles like Sudoku can be solved using DFS by exploring possible solutions depth-wise.
  - Ensures all potential paths are explored until the correct solution is found.

- Both visit the same set of nodes but in a different order.
- Both traverse all the edges in the connected component but in a different order.
- BFS trees have root-to-leaf paths that look as short as possible
- Paths in DFS trees tend to be long and deep.



# Implementation

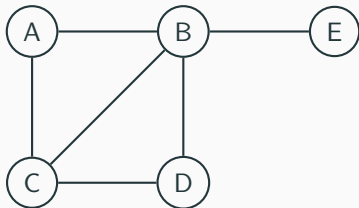
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# Implementation: Representing Graphs

- Graph  $G = (V, E)$  has two input parameters:  $|V| = n, |E| = m$ .
  - Size of the graph is defined to be  $m + n$ .
  - Strive for algorithms whose running time is linear in graph size, i.e.,  $O(m + n)$ .
- **Adjacency matrix:**  $n \times n$  Boolean matrix, where the entry in row  $i$  and column  $j$  is 1 if and only if the graph contains the edge  $(i, j)$ .
- **Adjacency list:** array  $Adj$ , where  $Adj[v]$  stores a linked list of all nodes adjacent to  $v$ .
  - An edge  $e = (u, v)$  appears twice: in  $Adj[u]$  and  $Adj[v]$ .

Operation/Space	Adj. matrix	Adj. list
Is $(i, j)$ an edge?	$O(1)$ time	$O(n_i)$
Iterate over all edges incident on node $i$	$O(n)$ time	$O(n_i)$
Space	$O(n^2)$	$O(n + m)$

## Graph Representations: Example



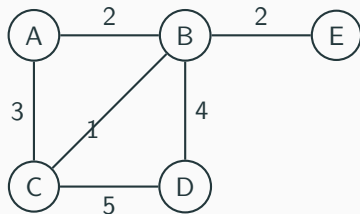
**Adjacency matrix representation**

	A	B	C	D	E
A	0	1	1	0	0
B	1	0	1	1	1
C	1	1	0	1	0
D	0	1	1	0	0
E	0	1	0	0	0

**Adjacency list representation**

V	Neighbors
A	B, C
B	A, C, D, E
C	A, B, D
D	B, C
E	B

## Graph Representations: Example 2



**Adjacency matrix representation**

	A	B	C	D	E
A	0	2	3	0	0
B	2	0	1	4	2
C	3	1	0	5	0
D	0	4	5	0	0
E	0	2	0	0	0

**Adjacency list representation**

V	Neighbors
A	B (2), C (3)
B	A (2), C (1), D (4), E (2)
C	A (3), B (1), D (5)
D	B (4), C (5)
E	B (2)

# Implementation: Traversal

- "Implementation" of BFS and DFS: fully specify the algorithms and data structures so that we can obtain provably efficient times.
- Inner loop of both BFS and DFS: process the set of edges incident on a given node and the set of visited nodes.
- How do we store the set of visited nodes? Order in which we process the nodes is crucial.
  - BFS: store visited nodes in a queue (first-in, first-out).
  - DFS: store visited nodes in a stack (last-in, first-out)

## Conclusion

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- We discussed the motivation behind graph data structures
- Problems that can be solved with graph modeling
- Definitions and properties
- Graph representations
- Graph traversal algorithms

- Greedy Algorithms
  - Both with linear and graphs data structures
  - More graph examples



# Acknowledgement

- Parts of the slides adopted from T. M. Murali @ VT